The operation and description of Philips LPC900 Series microcontroller such as P89LPC935 to Philips Bridge IC such as SC16IS750 for high-speed serial data communication is discussed in this application note. In addition, the source code in C language, containing communication routines between the P89LPC935 microcontroller and the SC16IS750 Bridge IC is provided. This application note is also applicable to other Bridge ICs such as SC16IS740, SC16IS760, SC16IS752, and SC16IS762.
# Contact information

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1. Introduction

The Philips Bridge IC is a new generation of interface solutions for managing high-speed serial data communication among various bus interfaces such as SPI, I²C-bus, and UART including RS-232 and RS-485. The Bridge IC is commonly used to overcome the limitation of the host bus interface to peripherals and to provide easy interface with existing different serial buses.

The description of the block diagram, hardware, firmware, and software are described in the next paragraphs for users to quickly understand the implementation of the Philips LPC900 Series microcontroller to Philips Bridge IC serial interface for RS-232 point-point communication, RS-485 multi-drop application, IrDA wireless links communication, and GPIO interface. The source code in C language is provided to show how to write a simple communication program between the microcontroller and the Bridge IC serial interface. The goal is to help users to design the Bridge IC in their application and also shorten their product development cycle.

2. Block diagram

The block diagram depicted in Figure 1 shows the circuit connection between a Philips Bridge IC such as SC16IS750 and Philips LPC900 Series microcontroller such as P89LPC935. The Bridge IC offers simple, flexible, and minimal connection to the microcontroller. The Bridge IC embedded SPI and I²C-bus for the host interface so the microcontroller can easily control the Bridge IC with four-wire connection through SPI or I²C-bus, which is a widely used serial bus interface. If the SPI-bus interface is selected, the Bridge IC can interface to the microcontroller with a 4-wire connection. The signals on the 4 wires are MISO (Master Input Slave Output), MOSI (Master Output Slave Input), CS (Chip Select), and SPICLK (SPI Clock). If the I²C-bus is selected, the Bridge can interface to the microcontroller with a 2-wire connection. The signals on the 2 wires are SCL (Serial Clock) and SDA (Serial Data).

After the microcontroller and Bridge IC are wired properly and their connection is established, the microcontroller can send data to and receive data from UART devices via the Bridge IC. The Bridge IC receives the data from the microcontroller via the SPI or I²C-bus interface and sends the data to the UART devices via RS-232 or RS-485 bus interface, and when the Bridge IC receives the data from the UART devices the Bridge IC will notify the microcontroller by generating an interrupt signal; then the microcontroller can access the data from the Bridge IC via the SPI or I²C-bus interface.

![Block diagram of Philips Bridge IC interface](image-url)
3. Hardware description

The hardware consists of the two major parts, which are the microcontroller and the Bridge IC. The Bridge IC provides a seamless interface convergence between the SPI or I²C-bus and RS-232 or RS-485 protocols and vice versa. In addition, the Bridge IC checks the data transmission for errors and maintains very high data throughput.

The functions of the two major parts are described as follows:

- **Philips P89LPC935 microcontroller**
  The microcontroller connection to the Bridge IC is through the SPI or I²C-bus interface. The microcontroller acts as a master controlling the Bridge IC with the embedded firmware code in the microcontroller ROM (Read Only Memory). The microcontroller initiates the data transfer on the bus and controls the Bridge IC with the chip select pin for SPI-bus interface.

- **Philips SC16IS750 Bridge IC**
  The Bridge IC acts as a slave interface convergence between the microcontroller and UART peripheral. The Bridge IC handles the SPI or I²C-bus interface to the microcontroller and the UART that consists of transmitter and receiver. The transmitter sends the data received from the microcontroller to the UART peripherals. The receiver sends the data received from the UART peripheral to the microcontroller.

The transceivers are optional and can be intended for RS-232 or RS-485 communication interface. The transceivers consist of drivers and receivers. The drivers convert the UART-logic output levels to RS-232 or RS-485 signals, whereas the receivers convert the RS-232 or RS-485 signals to UART-logic input levels. If the UART-logic level conversion is not required, the transceivers are optional.

For hardware connection details, please refer to the schematic shown in Figure 2 and Figure 3.
Fig 2. Schematic diagram (part 1)
Fig 3. Schematic diagram (part 2)
4. Software description

The programming of the Bridge IC can be done by writing firmware code, which requires the following software:

- Keil is one of the embedded system vendors that provide the software development tools for Philips P89LPC935 microcontroller. The software compiles the firmware code written in C and generates an ‘Intel Hex’ file. The software evaluation development kit can be downloaded from the Keil website.

- "Flash Magic" is free Windows application software that allows easy programming of Philips P89LPC935 microcontroller. The software loads the ‘Intel Hex’ file to the microcontroller by using its in-system programming mode communicating through serial port. The software can be downloaded from the Embedded Systems Academy website under “Flash Magic”.

5. In-System Programming mode

Philips P89LPC935 microcontroller has an on-chip Flash program memory with ISP (In-System Programming) that allows the microcontroller to be programmed without removing the microcontroller from the board, and also the microcontroller, which if previously programmed can be reprogrammed without removal from the board.

The microcontroller must be powered up in a special ‘ISP mode’ to perform the ISP operation. The ISP mode allows the microcontroller to communicate with a host device such as PC through a serial port. The host sends commands and data to the microcontroller. The commands can be erase, read, and write. After the completion of the ISP operation, the microcontroller is reconfigured and has to be reset or power cycled so the microcontroller will operate normally.

The ISP programming for the device can be done using a Windows application software, which uses an Intel Hex file as input to program it. For more information about the software, please refer to Section 4 “Software description”.

6. Firmware description

The firmware code for the P89LPC935 microcontroller is written in C language. It can be compiled by using an embedded C compiler. For more information about the compiler, please refer to Section 4 “Software description”.

The firmware code consists of three major blocks: Main Loop, Interrupt Service Routine, and Bus Interface layer, and are described in

6.1 Main Loop

The function of the Main Loop is to reset and initialize the Bridge IC by writing a character to the Bridge IC’ register. Inside the Main Loop, the microcontroller can select one of the two methods for communicating to the Bridge IC. The first method is polling the Bridge IC’ status register regularly. The second method is using an interrupt handler in the Interrupt Service Routine until the Bridge IC generates an interrupt. If using the interrupt handler,
the microcontroller and the bus interrupt bits must be enabled. The other function of the Main Loop is to keep checking the event flags and pass to the appropriate subroutine for further processing.

6.2 Interrupt Service Routine

The microcontroller uses the Interrupt Service Routine (ISR) to handle an interrupt generated by the Bridge IC. As soon as the Bridge IC generates an interrupt, the ISR checks the interrupt status of the Bridge IC to determine the interrupt type and sets up proper event flags to inform the Main Loop program for processing the interrupt request.

6.3 Bus interface layer

The bus interface layer handles the SPI or I2C-bus interface between the microcontroller and the Bridge IC. The three functions in the bus interface layer are:

- **BusInterface_Init**: The microcontroller initialize the SPI or I2C-bus controller to initiate the SPI or I2C-bus data transfer.
- **BusInterface_Read**: The microcontroller reads data from the SPI or I2C-bus and stores the data for further processing.
- **BusInterface_Write**: The microcontroller writes data to the SPI or I2C-bus for the Bridge IC to read.

7. Conclusion

Philips Bridge IC provides easy interface to a host controller such as Philips P89LPC935 microcontroller, enables seamless and high-speed SPI or I2C-bus to RS-232 or RS-485 protocols convergence including GPIO for general-purpose input/output and IrDA for wireless links, and offers low voltage operation, low power consumption, and compact design which is suitable for battery-operated applications. In addition, the Bridge IC reduces software overhead, frees up the host controller resources, increases design flexibility, and improves overall system performance. For more details about the Bridge ICs, please download the data sheets from the Philips Semiconductors website under "Interface & Control, UARTs".
8. Legal information

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